

Contents

Preface	v
Preface to the second edition	vii
Part I	
NEWTONIAN MECHANICS	1
Chapter 1	
Experimental facts	3
1. The principles of relativity and determinacy	3
2. The galilean group and Newton's equations	4
3. Examples of mechanical systems	11
Chapter 2	
Investigation of the equations of motion	15
4. Systems with one degree of freedom	15
5. Systems with two degrees of freedom	22
6. Conservative force fields	28
7. Angular momentum	30
8. Investigation of motion in a central field	33
9. The motion of a point in three-space	42
10. Motions of a system of n points	44
11. The method of similarity	50
Part II	
LAGRANGIAN MECHANICS	53
Chapter 3	
Variational principles	55
12. Calculus of variations	55
13. Lagrange's equations	59

Contents

14. Legendre transformations	61
15. Hamilton's equations	65
16. Liouville's theorem	68
Chapter 4	
Lagrangian mechanics on manifolds	75
17. Holonomic constraints	75
18. Differentiable manifolds	77
19. Lagrangian dynamical systems	83
20. E. Noether's theorem	88
21. D'Alembert's principle	91
Chapter 5	
Oscillations	98
22. Linearization	98
23. Small oscillations	103
24. Behavior of characteristic frequencies	110
25. Parametric resonance	113
Chapter 6	
Rigid bodies	123
26. Motion in a moving coordinate system	123
27. Inertial forces and the Coriolis force	129
28. Rigid bodies	133
29. Euler's equations. Poinsot's description of the motion	142
30. Lagrange's top	148
31. Sleeping tops and fast tops	154
Part III	
HAMILTONIAN MECHANICS	161
Chapter 7	
Differential forms	163
32. Exterior forms	163
33. Exterior multiplication	170
34. Differential forms	174
35. Integration of differential forms	181
36. Exterior differentiation	188
Chapter 8	
Symplectic manifolds	201
37. Symplectic structures on manifolds	201
38. Hamiltonian phase flows and their integral invariants	204
39. The Lie algebra of vector fields	208
40. The Lie algebra of hamiltonian functions	214

41. Symplectic geometry	219
42. Parametric resonance in systems with many degrees of freedom	225
43. A symplectic atlas	229
Chapter 9	
Canonical formalism	233
44. The integral invariant of Poincaré–Cartan	233
45. Applications of the integral invariant of Poincaré–Cartan	240
46. Huygens’ principle	248
47. The Hamilton–Jacobi method for integrating Hamilton’s canonical equations	258
48. Generating functions	266
Chapter 10	
Introduction to perturbation theory	271
49. Integrable systems	271
50. Action-angle variables	279
51. Averaging	285
52. Averaging of perturbations	291
Appendix 1	
Riemannian curvature	301
Appendix 2	
Geodesics of left-invariant metrics on Lie groups and the hydrodynamics of ideal fluids	318
Appendix 3	
Symplectic structures on algebraic manifolds	343
Appendix 4	
Contact structures	349
Appendix 5	
Dynamical systems with symmetries	371
Appendix 6	
Normal forms of quadratic hamiltonians	381
Appendix 7	
Normal forms of hamiltonian systems near stationary points and closed trajectories	385
Appendix 8	
Theory of perturbations of conditionally periodic motion, and Kolmogorov’s theorem	399

Contents

Appendix 9	
Poincaré's geometric theorem, its generalizations and applications	416
Appendix 10	
Multiplicities of characteristic frequencies, and ellipsoids depending on parameters	425
Appendix 11	
Short wave asymptotics	438
Appendix 12	
Lagrangian singularities	446
Appendix 13	
The Korteweg–de Vries equation	453
Appendix 14	
Poisson structures	456
Appendix 15	
On elliptic coordinates	469
Appendix 16	
Singularities of ray systems	480
Index	511